Calibration of a Terrestrial Full Waveform Laser Scanner

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Agenda

- 1. Introduction & Motivation
- 2. Method
- 3. Dataset
- 4. Results & Analysis
 - System Response Model
 - Absolute Reflectance
 - Incidence Angle
 - Waveform Fitting
- 5. Future Direction

Introduction: Full Waveform LiDAR

- LiDAR = <u>Light</u> <u>D</u>etection <u>And</u> <u>R</u>anging
- Discrete LiDAR
 - XYZ, Intensity
- Full Waveform LiDAR
 - Digitized record of return echo waveform
 - Derive XYZ, Peak Amplitude (Intensity)



Introduction: Full Waveform LiDAR

• Primarily used to extract additional echoes (e.g., Gaussian fitting)



- Fitting parameters also used for target property extraction
- Most research has relied upon airborne sensors
- Terrestrial full waveform laser scanners allow control of illuminated targets, enabling more more robust calibration methods

Motivation for Calibration

Potential: Each digitized echo waveform contains information about the target radiometric and geometric properties

Waveform Intensity/Amplitude

- Discrete intensity and digitized waveform amplitude scales are arbitrary
- No link between these scales and a target's physical reflectance value

Radiometric Calibration:

- Establishes a link between peak waveform amplitude and target reflectance
- Reflectance value at laser wavelength provides target spectral property information

Motivation for Calibration

Potential: Each digitized echo waveform contains information about the target radiometric and geometric properties

Waveform Fitting

- Parametric model fitting struggles with complex system response shapes
- Sub-optimal models produce improper parameter extraction and decreased ranging accuracy (examples on next slide)

System Response Calibration:

- Determines the system response shape for ideal waveform fitting
- Analysis of deviations from fitted system response models may yield information on target geometric properties

Motivation for Calibration



Method – Radiometric Calibration

Goal = link peak waveform amplitude to target reflectance

- 1. Store peak waveform amplitude from targets of known reflectance
- 2. Measurements at multiple ranges
 - Range attenuation
 - System nonlinearity
 - ~Atmospheric attenuation
- 3. Result = Table of Amplitude vs. Reflectance vs. Range
 - Empirical, system specific
 - Estimate target reflectance from any subsequent waveform



Method – System Response Calibration

Goal = System response model spanning dynamic range

- 1. Utilize the radiometric calibration measurements
- 2. Store average waveform
 - Same target, normal incidence
 - Span detector dynamic range
- **3**. Result = Table of system response waveform shapes
 - Empirical, System Specific
 - Accommodates system non-linearity
 - Ideal fitting model for any amplitude waveform return
- Note
 - Ideally, the emitted laser pulse is sampled
 - Practical alternative is to measure target with known, standard properties

Dataset

- Riegl VZ-400 with full waveform option
 - 1550 nm laser wavelength
 - ~ 5-7 ns FWHM pulse width
 - Two modes: Long Range & <u>High Speed</u>
 - Two detector channels: High power & Low power
- Labsphere Spectralon: 20% (32%), 50% (60%), 99% reflectivity



Dataset

- Measurement ranges:
 - 2 32 m: 2 m increments
 - 35 70 m: 5 m increments
 - 80 140 m: 10 m increments
 - 160 260 m: 20 m increments
- Incidence angles
 - 0°, 20°, 40°, 60°
 - 99% Spectralon only
- Sparse waveforms
 - 500 MHz (2 ns) digitizer
 - 5-7 ns pulse width



Typical VZ-400 Waveform

Results: System Response Model



- 1. Sparse single waveform
- 2. Several thousand aligned waveforms at each range
- Each aligned set of waveforms averaged and combined to form a system response model



Results: System Response Model

• Nonlinear response at high amplitudes



Stored in table format for simple interpolation at any desired amplitude or range

Results: Absolute Reflectance

 Peak waveform amplitudes are not proportional to absolute reflectance until beyond ~175 m



Estimated target reflectance for a given range and peak amplitude is easily interpolated

Results: Incidence Angle



- 1. Peak amplitude does not follow cosine law until range > ~150 m
- 2. Increased incidence angle does not increase waveform width
 - Small beam divergence/footprint
 - Width increase below digitizer resolution
- Target incidence angle information limited to peak amplitude

Results: Least Squares Waveform Fit

- Problem: The model is a table of numbers (no parameters)
- Requires assumptions about underlying "function model" (f)
 - Assumed function model is clearly non-linear
 - Partial derivatives of f w.r.t. amplitude (A) and time location (μ):

$$\frac{\partial f}{\partial A} = Normalized Template Waveform$$
$$\frac{\partial f}{\partial \mu} = -Slope Template Waveform$$

 Partial derivatives can be evaluated numerically from the calibrated system response data

Results: Least Squares Waveform Fit



- Each iteration utilizes a unique interpolated system response waveform from the calibrated model
- Elevated tail accommodated very well by calibrated system response model
- Enables analysis of deviations from standard system response

Future Direction

- Collect calibration data with additional laser wavelength
 - 1064 nm collection scheduled for May 2013
 - Examine potential for target identification via spectral analysis
- System response deviation analysis
 - Echo waveform deviation from fitted system response
 - Analysis for correlation to target properties
- Multi-target waveforms
 - Accommodate target cross-section for more relevant reflectance values in complex multi-target waveforms

Wrap-Up

- 1. Instrument calibration achieved via stored measurements of standard reflectance targets at multiple ranges.
- 2. Radiometric calibration enables estimation of target absolute reflectance.
- 3. System response calibration enables ideal waveform echo fitting for precise ranging and deviation measure.
- The combination of target reflectance and echo waveform deviation will be investigated for enhanced target identification.

Thank you

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